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# Efficient Semantic Deduction and Approximate Matching over Compact Parse Forests

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# Our RTE-3 Recipe

1. Represent  $t$  and  $h$  as parse trees
2. Try to prove  $h$  from  $t$  based on available knowledge
3. Measure the “distance” from  $h$  to the generated consequents of  $t$ .
4. Determine entailment based on distance
5. Cross your fingers ...  
*I forgot one thing...*

6. **Wait a few hours...**

**This year: hours → minutes**



# Textual Entailment –

## Where do we want to get to?

- Long term goal:
  - ***robust semantic inference engine***
  - To be used as a generic component in text understanding applications
  - Encapsulating all required inferences
- Based on compact, well defined formalism:
  - Knowledge representation
  - Inference mechanisms

# Our Inference Formalism

Bar-Haim et al., AAAI-07 & RTE3

- A **proof system** over parse trees:
  - Represents diverse kinds of semantic knowledge uniformly as entailment (inference) rules
  - Allows unified inference mechanism

■ Analogous to logic proof systems:

Propositions	Parse Trees
Inference Rules	Tree transformations
Proof	A sequence of trees, generated by rule application

- Given *Text* ( $T$ ) and *Hypothesis* ( $H$ ), try to generate  $H$  from  $T$
- Formalizes common transformation-based approaches

# A Sample Proof

**Text:** McCain congratulated the elected president, Barack Obama.

## Consequent

⇒ Barack Obama is the elected president.

⇒ Barack Obama won the elections

⇒ The Democratic nominee won the elections.

## Entailment Rule

*Apposition*  
(syntactic)

*X is the elected president*  
→ *X won the elections*  
(lexical-syntactic)

*Barack Obama*  
→ *the Democratic nominee*  
(lexical)

**Hypothesis:** The Democratic nominee won the elections.

# Explicit Generation of Consequents

**Text:** Children like candies.

**Rules:** *children* → *kids* ; *like* → *enjoy* ; *candies* → *sweets*

**Consequents:**

Kids like candies.

Kids enjoy candies.

Children like sweets.

...

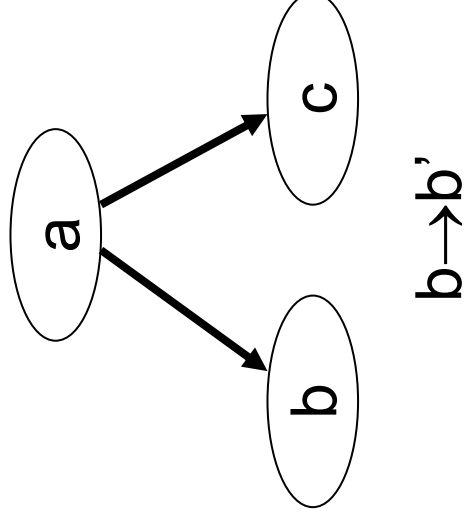
**$2^3$  alternatives!**



We need compact representation of consequents!

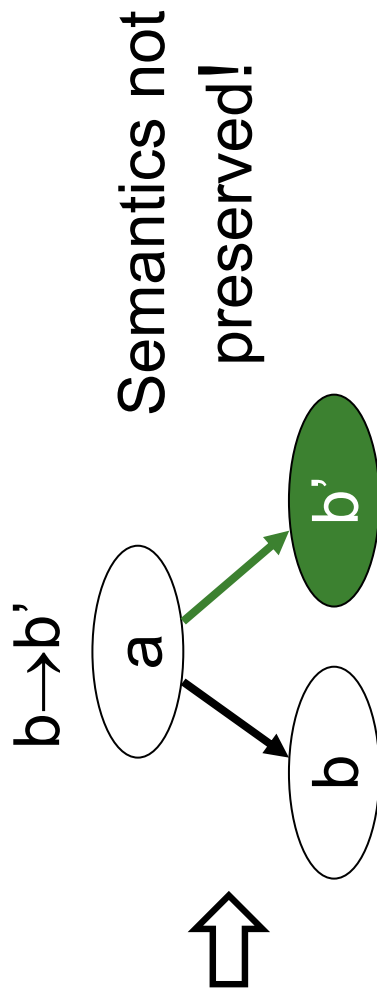
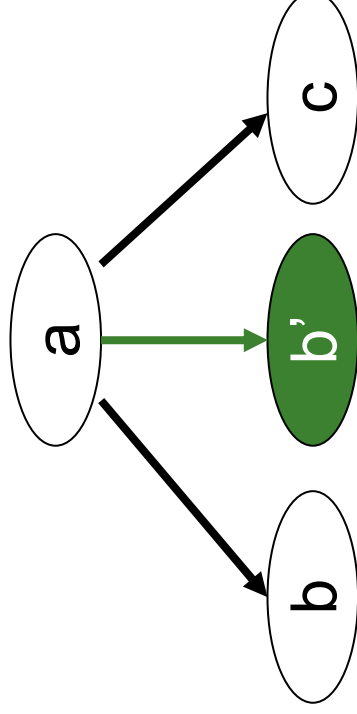
## Intuitive Solution: Add only the Entailed Part

- Resulting structure is a union of sentences (trees)
- Each of its sub-structures is assumed to be entailed



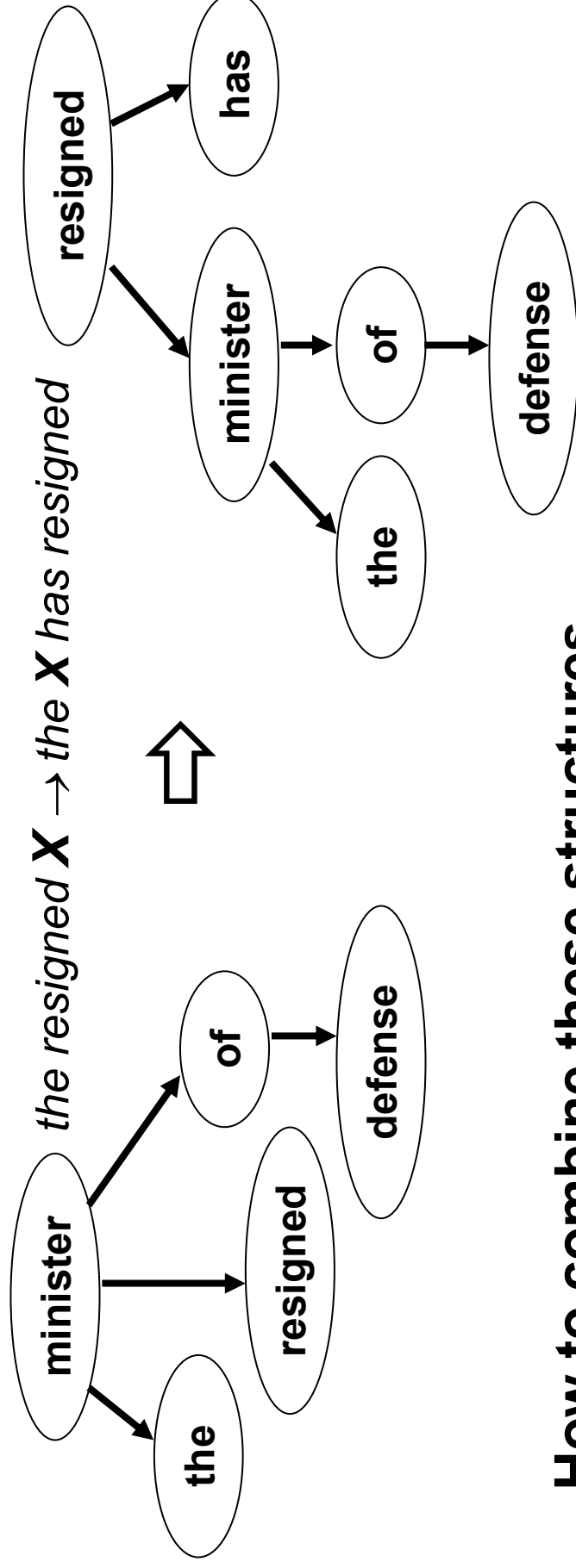
## Intuitive Direction: Add only the Entailed Part

- Resulting structure is a union of sentences (trees)
- Each of its sub-structures is assumed to be entailed





# How to share common variables?



**How to combine these structures efficiently (and correctly)?**

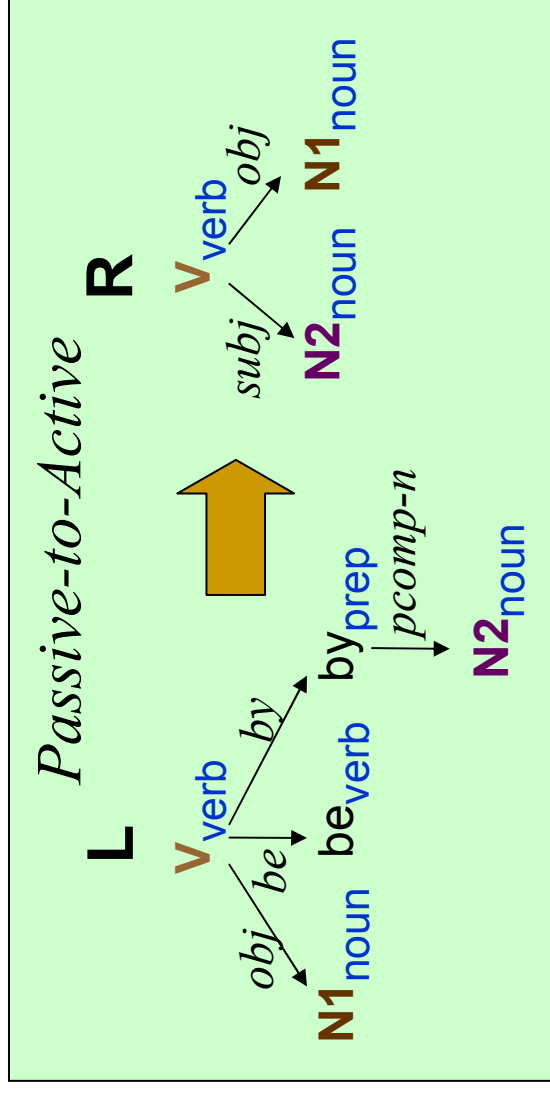
# Talk Outline


- A novel data structure, **compact forest**, for efficient inference
  - Preserves semantics
- New sources of entailment rules
  - Scale made feasible by compact forest
- Approximate matching
- Results

# The Compact Forest

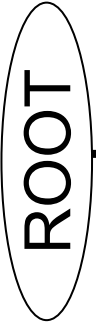
# The Compact Forest – a Walk-Through Example

- A sample rule: passive-to active transformation



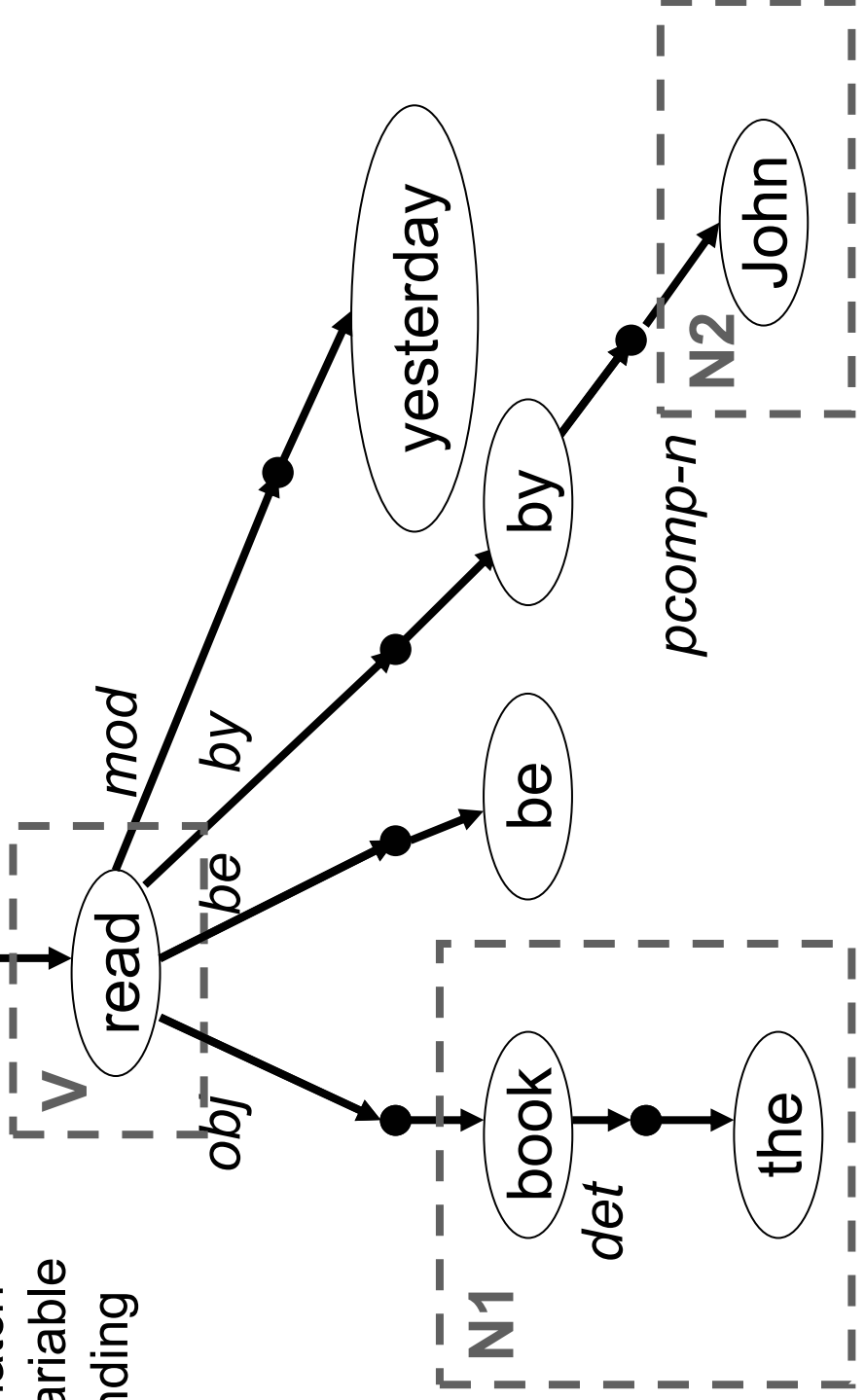
The book was read by John yesterday  John read the book yesterday

Initial compact forest

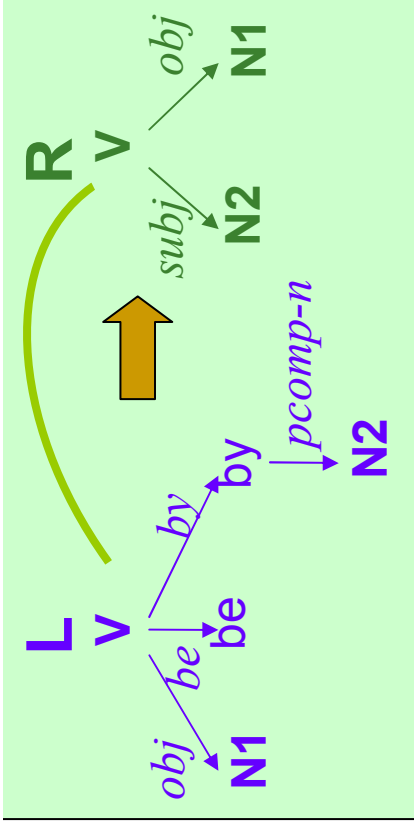


*i*

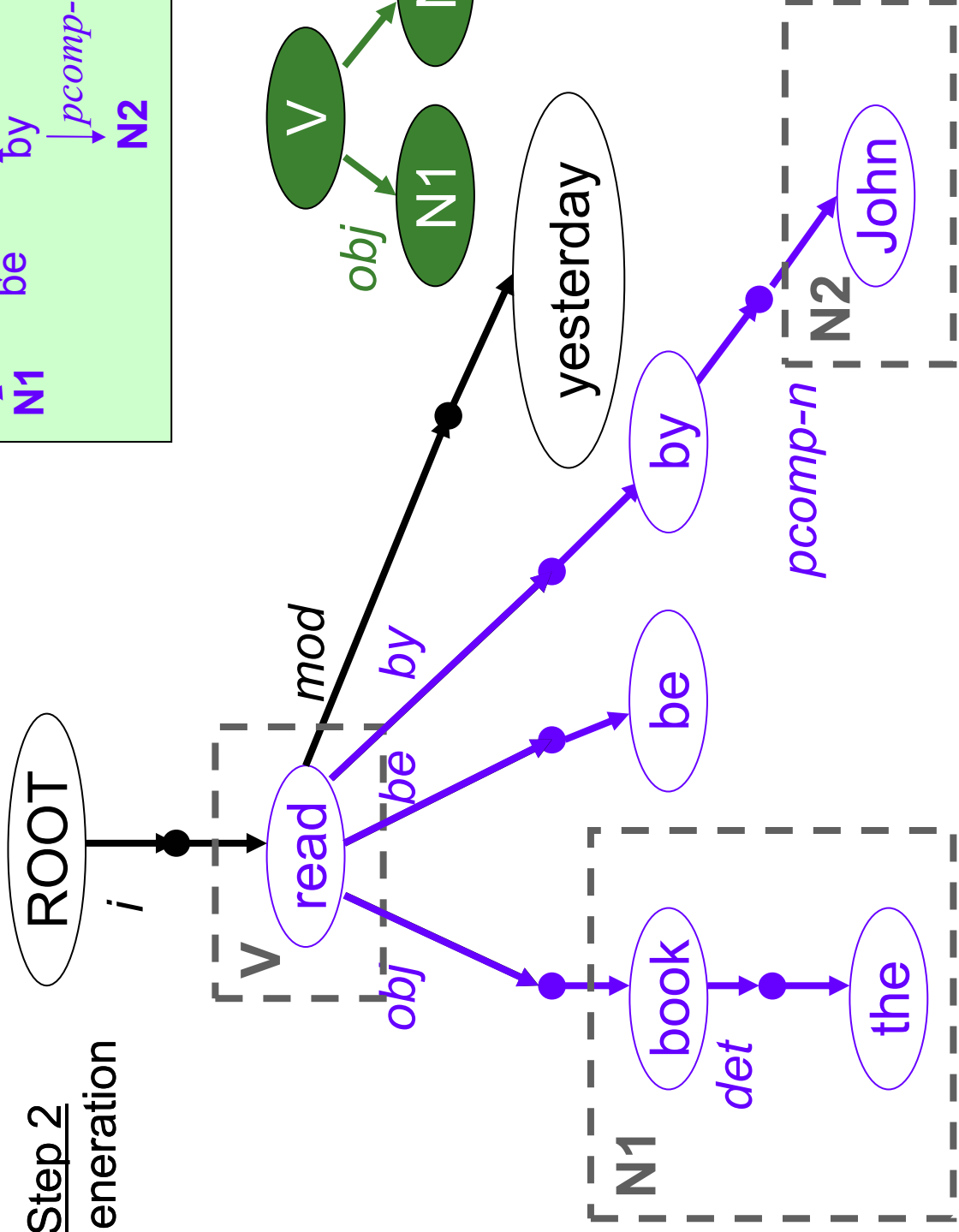
Step 1  
L match  
& Variable  
Binding



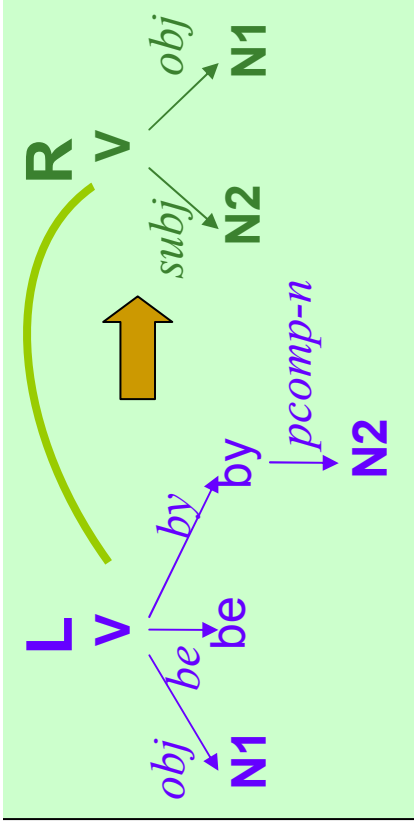
The book was read by John yesterday



Step 2  
R generation

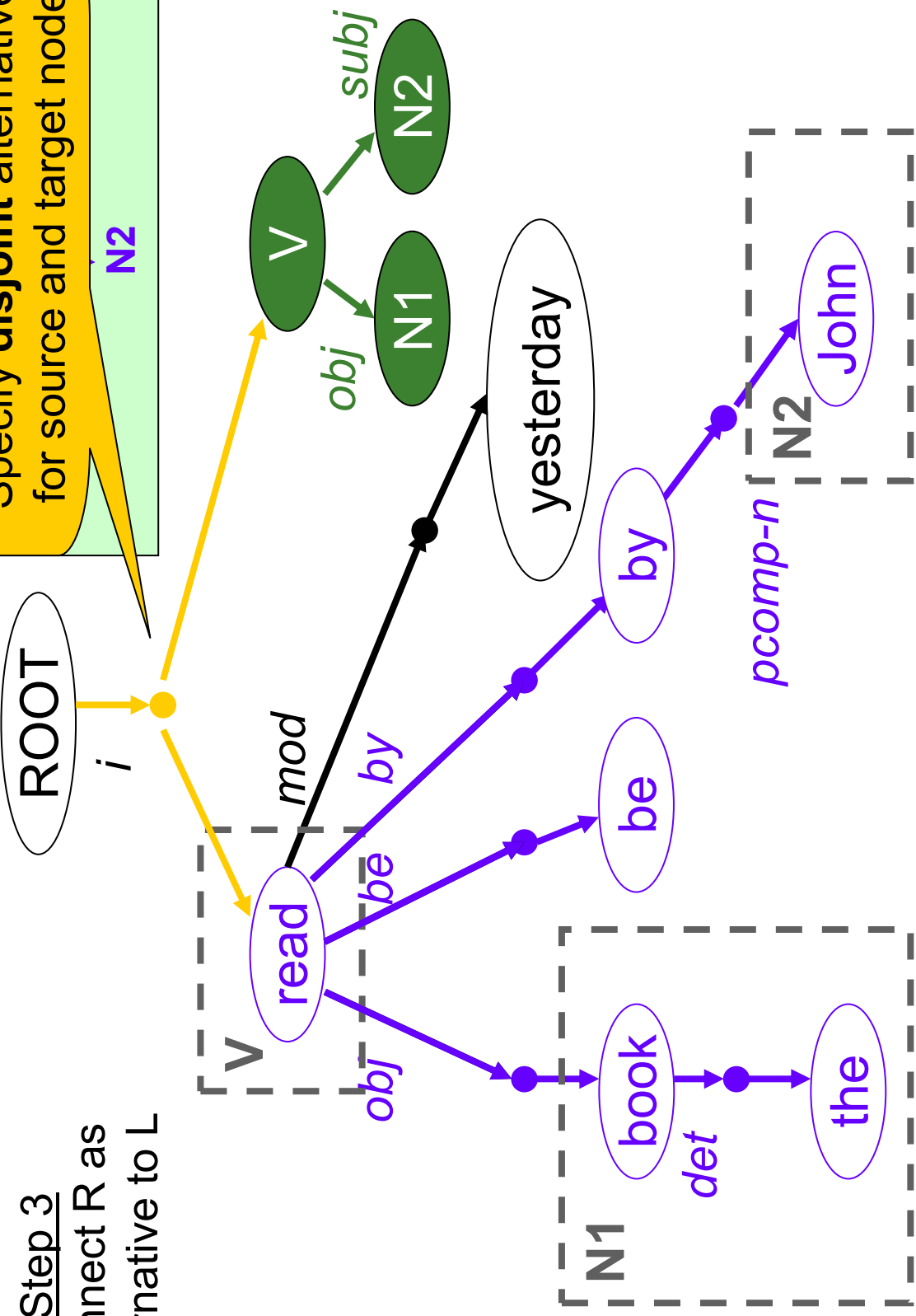


The book was read by John yesterday



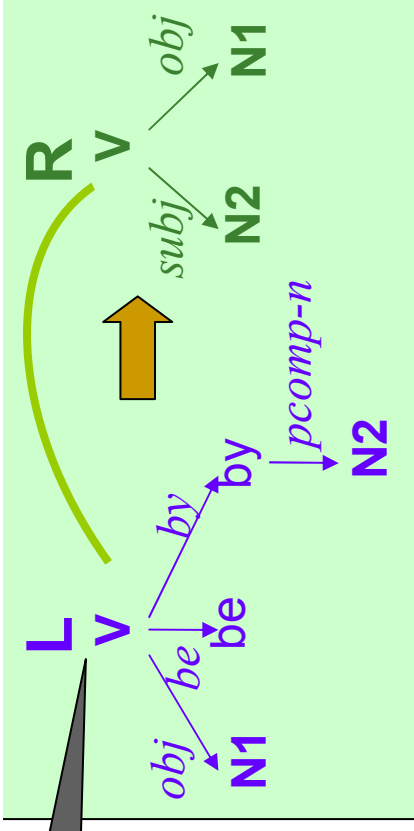
Step 3  
 Connect R as  
 alternative to L

Disjunction edges (*d*-edges)  
 Specify **disjoint** alternatives  
 for source and target nodes

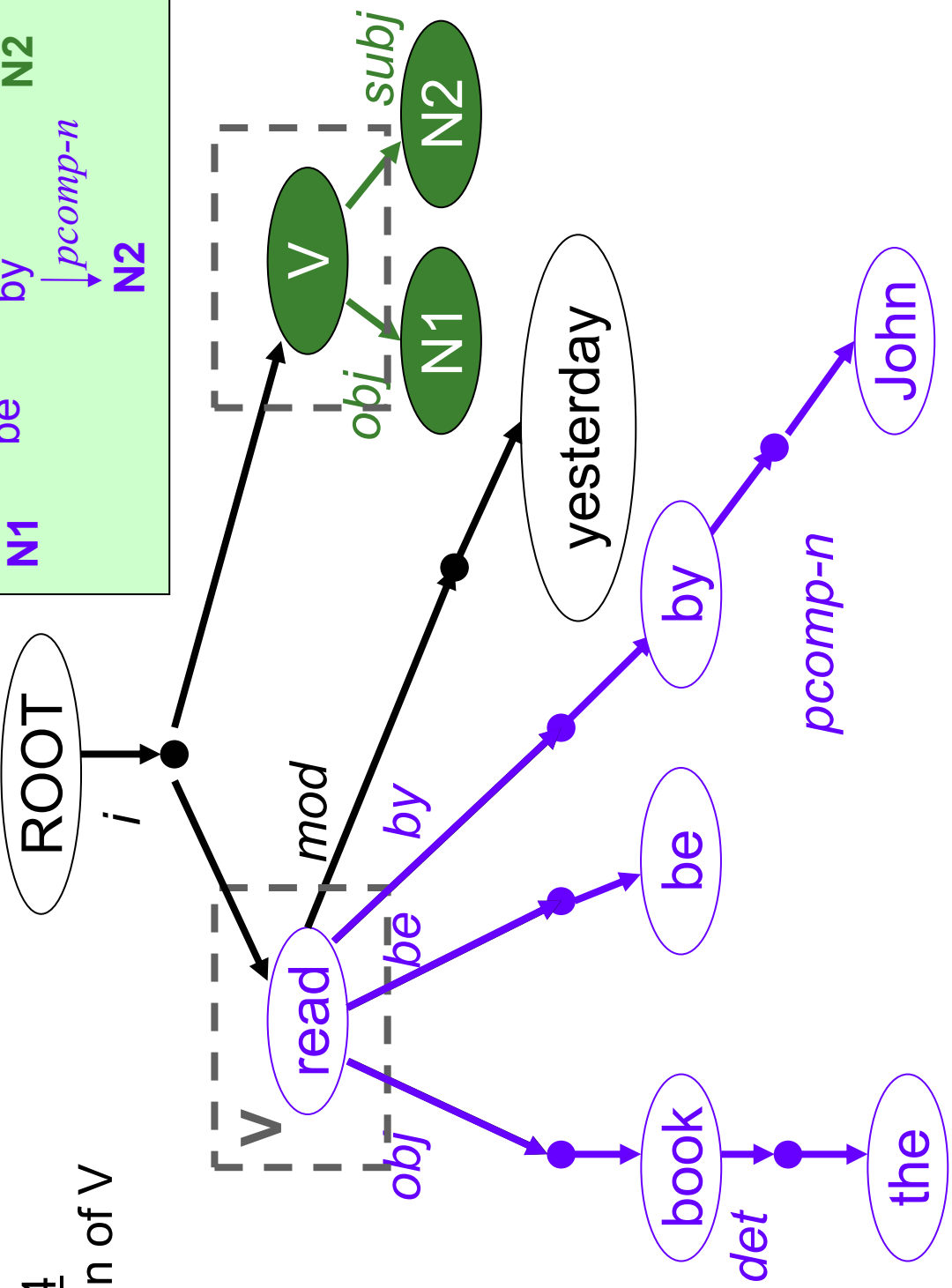


The book was read by John yesterday  $\Rightarrow$  N1 V N2

V has different modifiers in L and R  $\Rightarrow$  should be copied



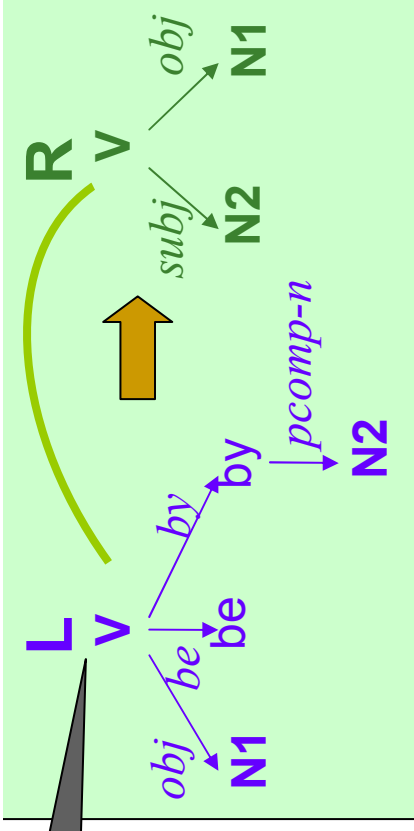
Step 4  
instantiation of V



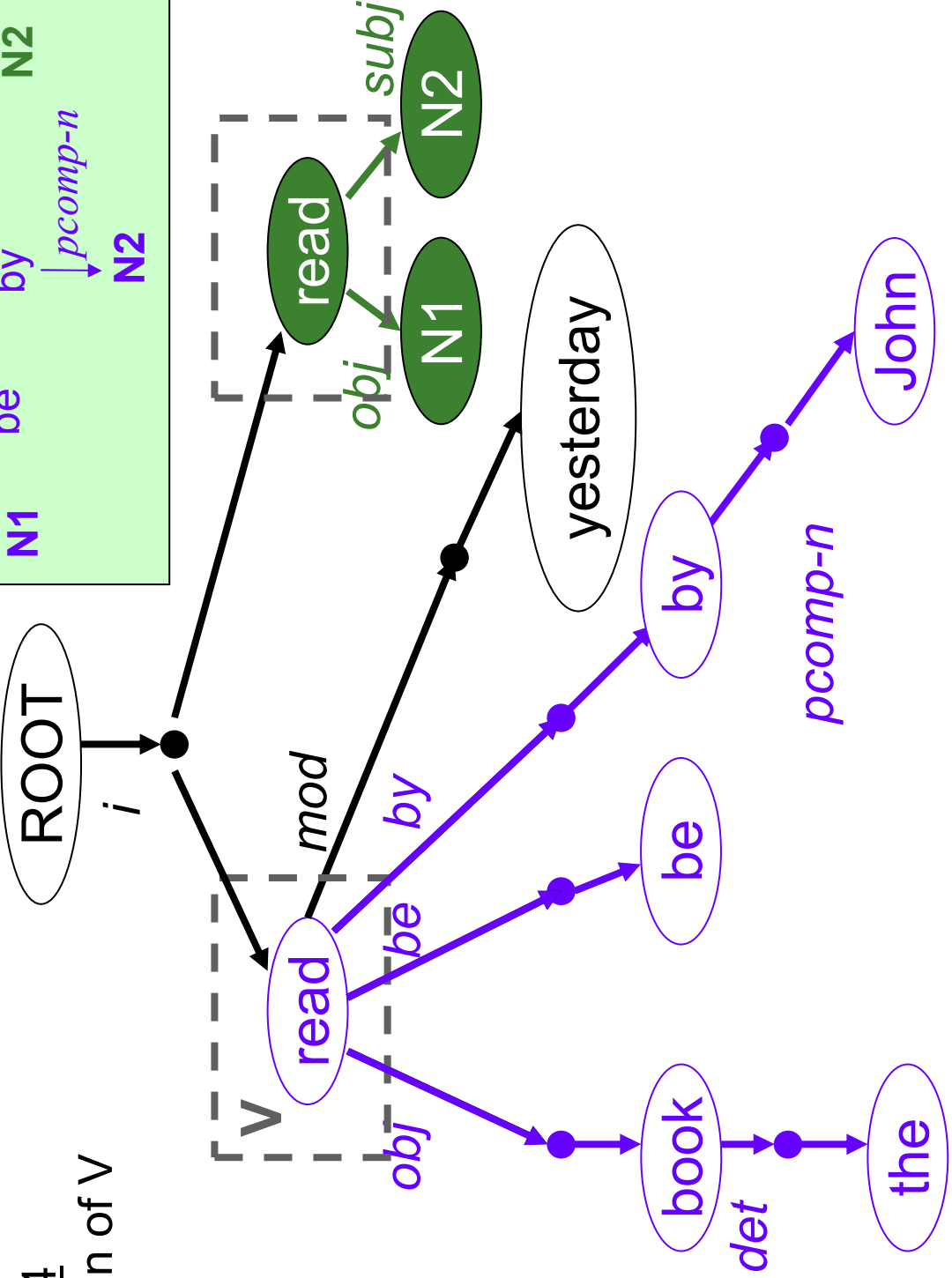
The book was read by John yesterday  $\Rightarrow$  N1 V N2



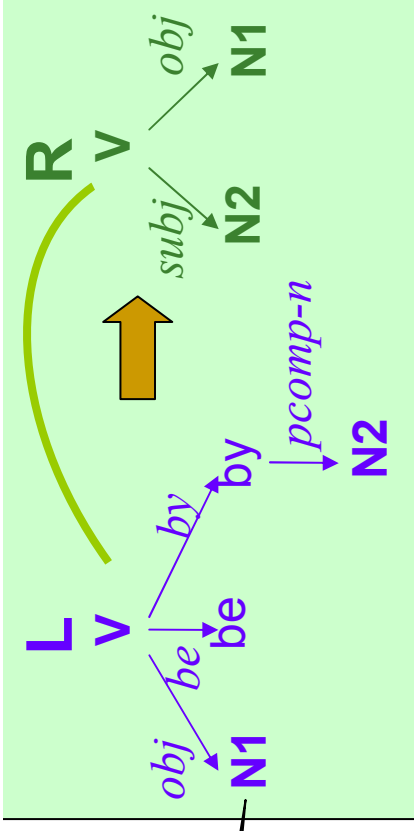
V has different modifiers in L and R ⇒ should be copied



Step 4  
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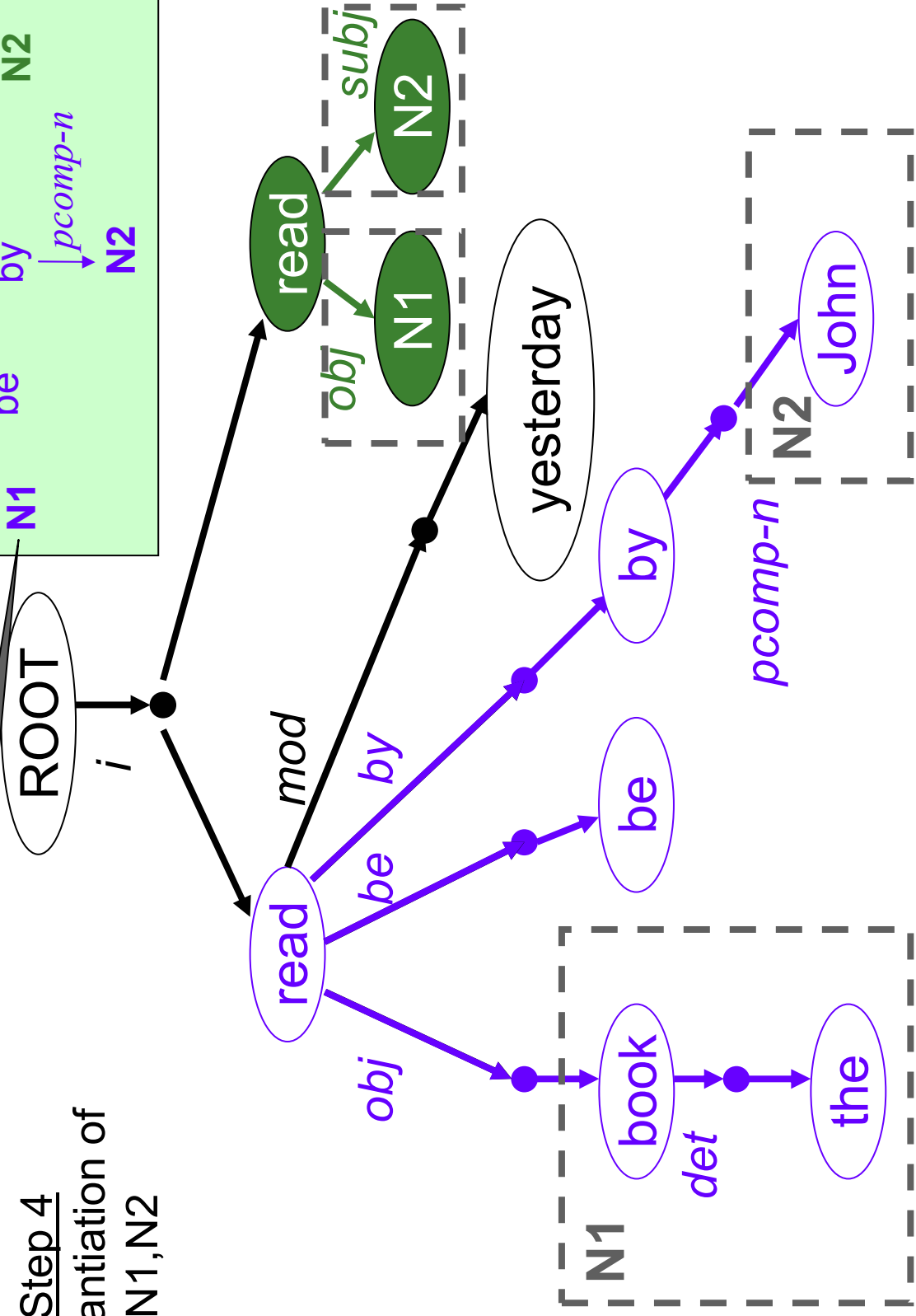


The book was read by John yesterday ⇒ N1 read N2

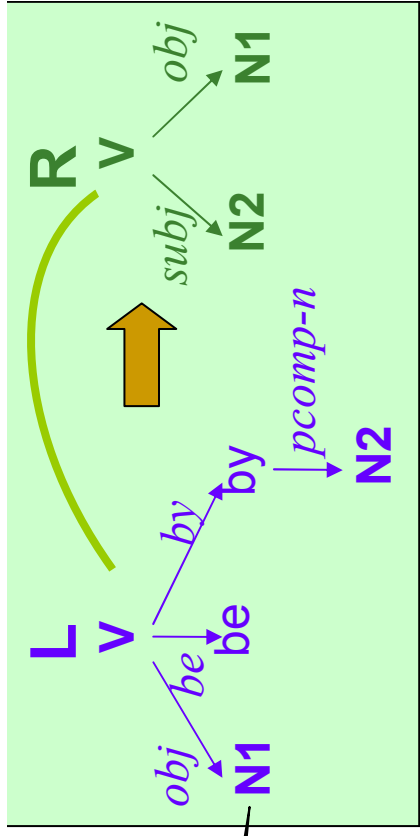


N1 and N2 are leaf variables in L and R ⇒ can be shared

Step 4  
instantiation of  
N1, N2

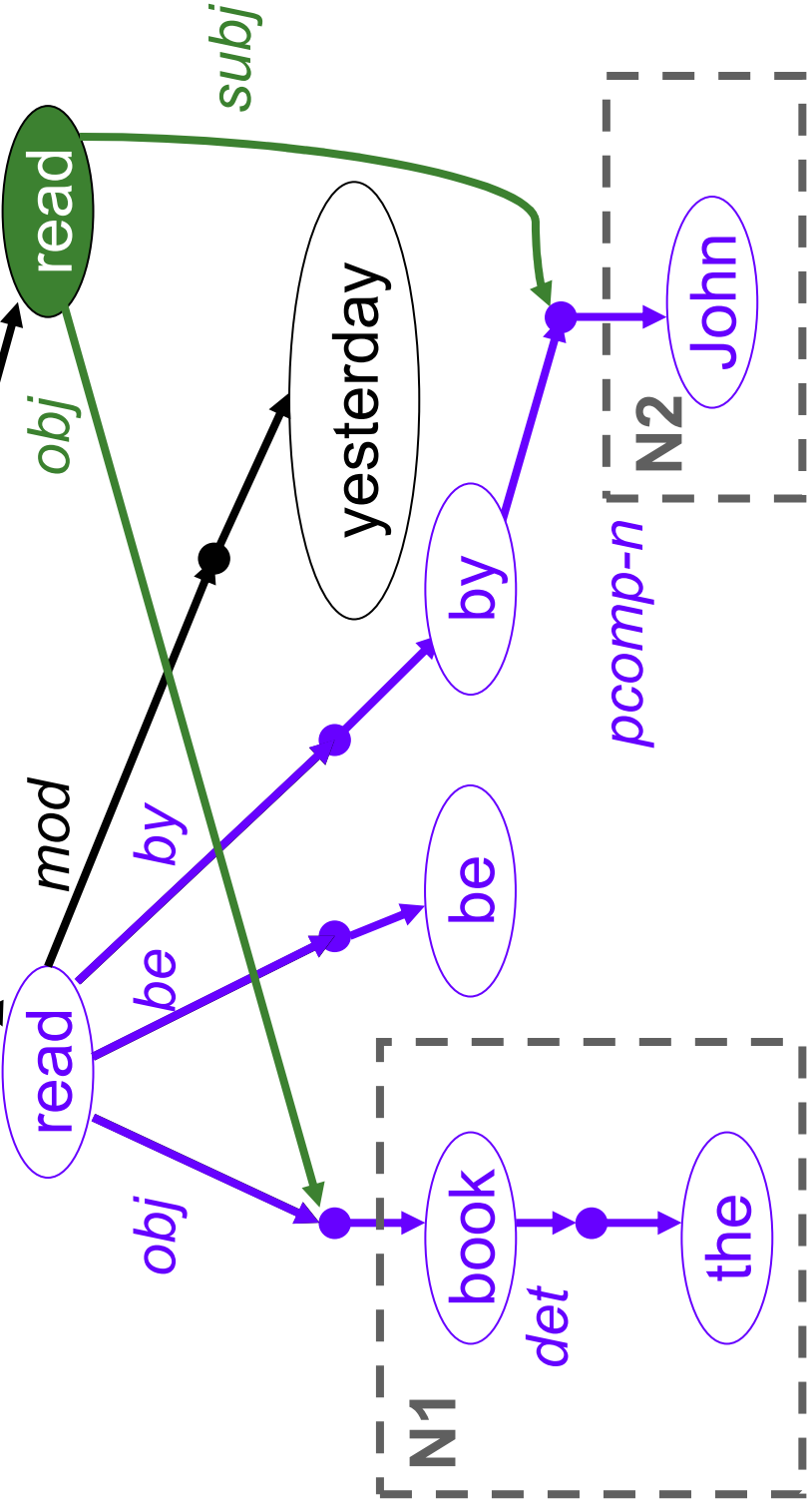


The book was read by John yesterday ⇒ N1 read N2

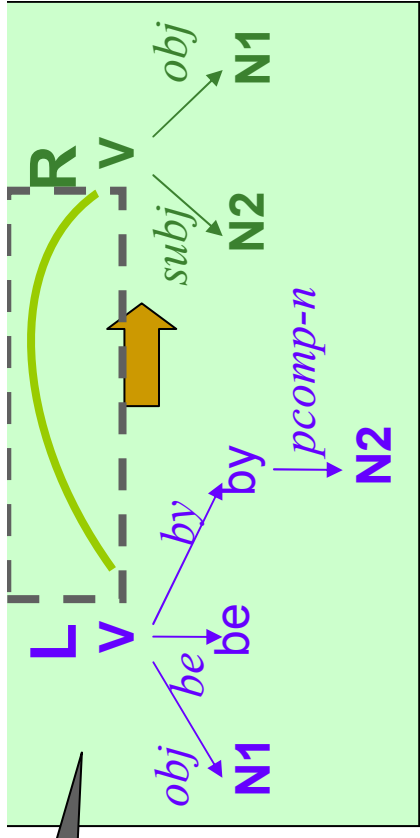


N1 and N2 are leaf variables in L and R  
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Step 4  
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 N1, N2

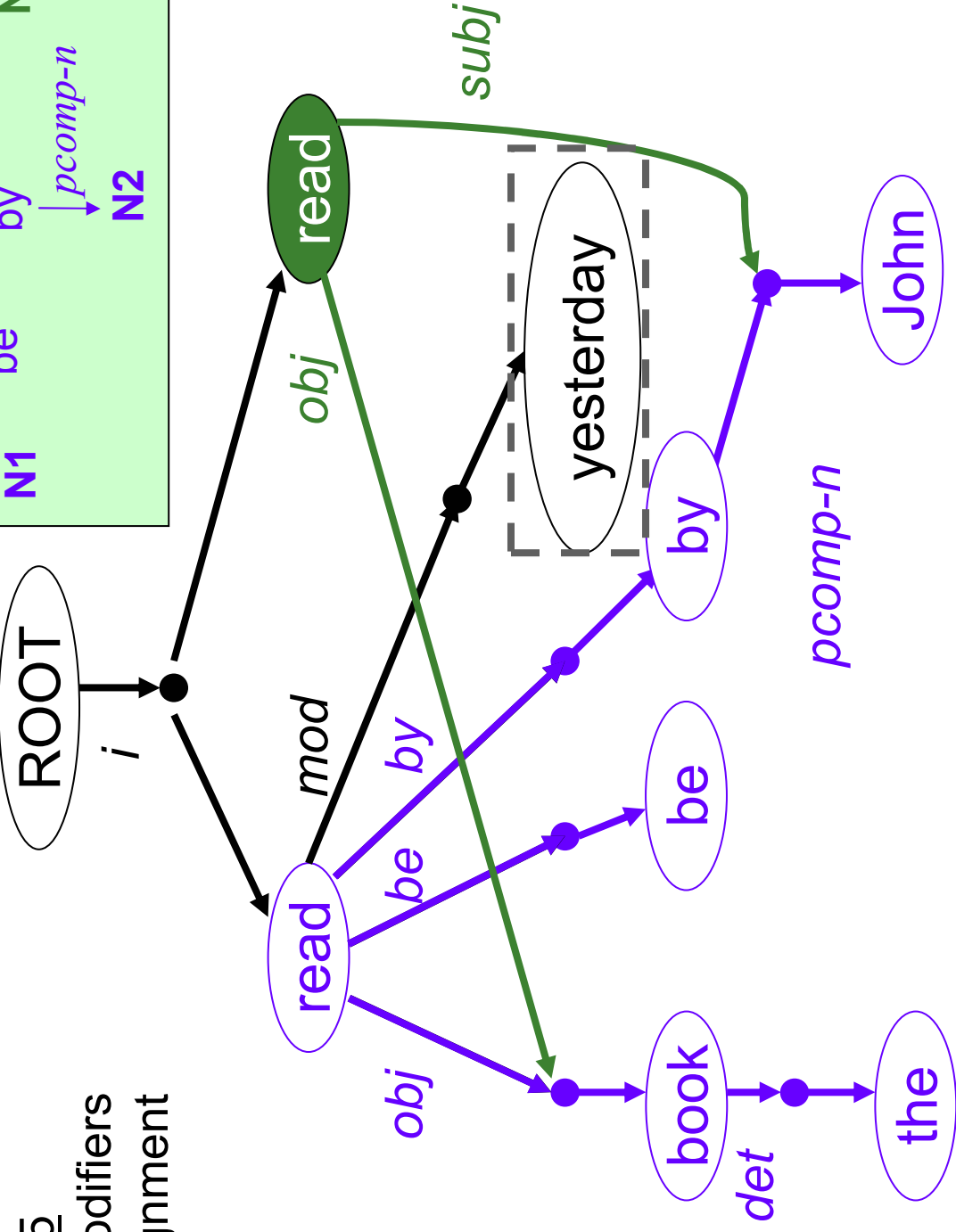


The book was read by John yesterday ⇒ John read the book

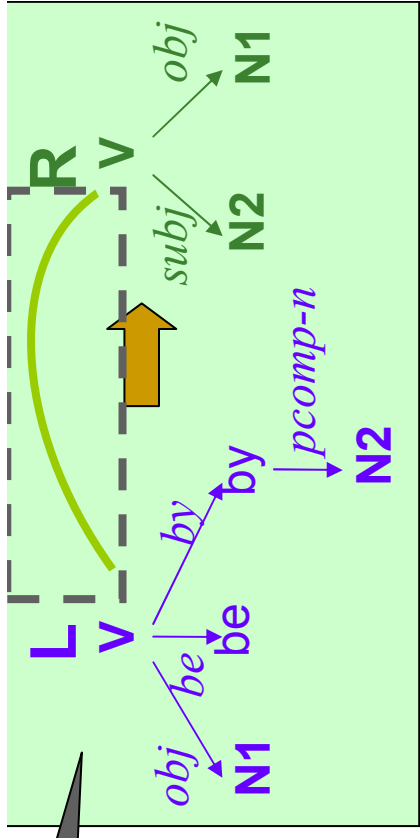


Alignment arc indicates modifier copying to R

Step 5  
Sharing modifiers through alignment



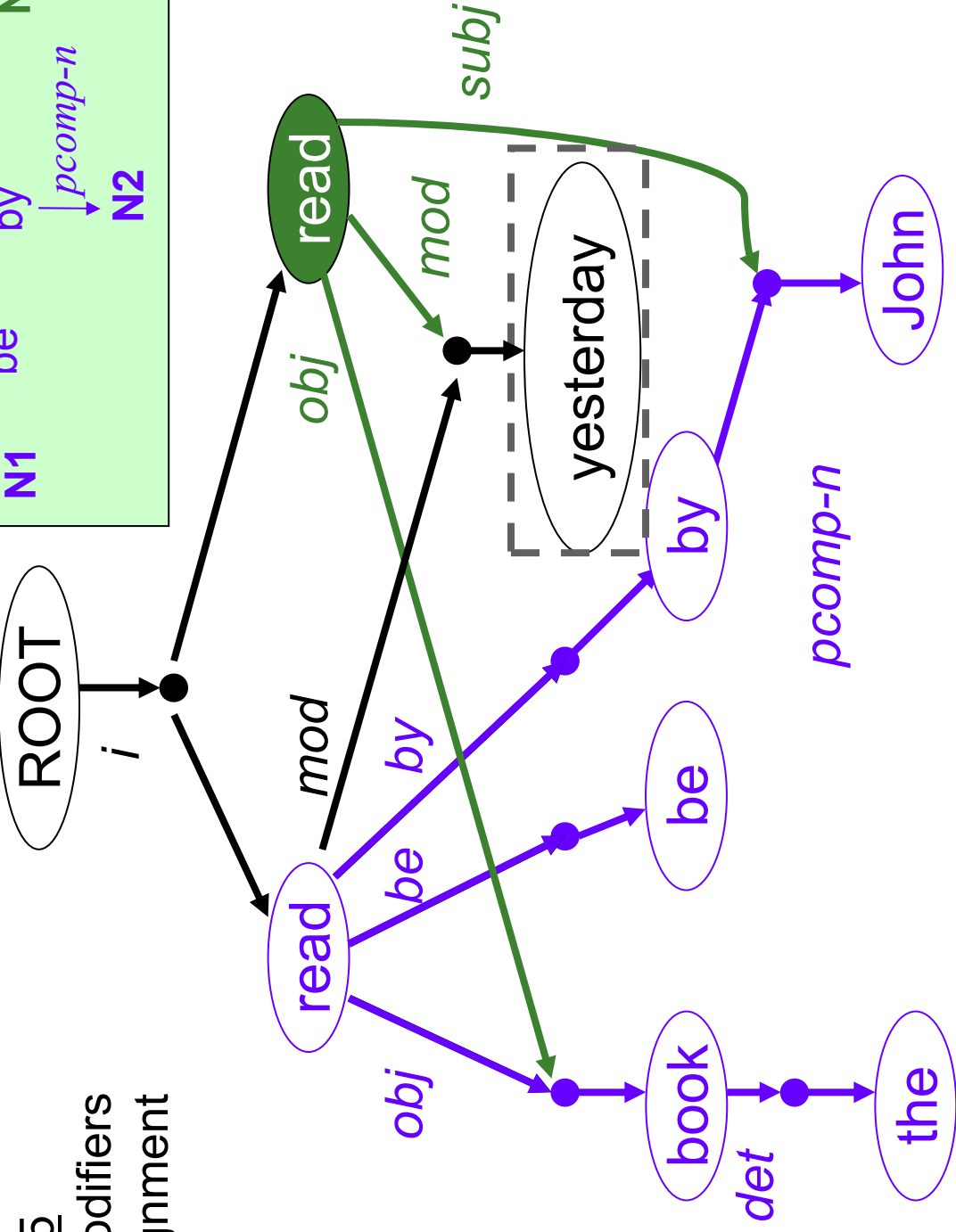
The book was read by John yesterday ⇒ John read the book



Alignment arc indicates modifier copying to R

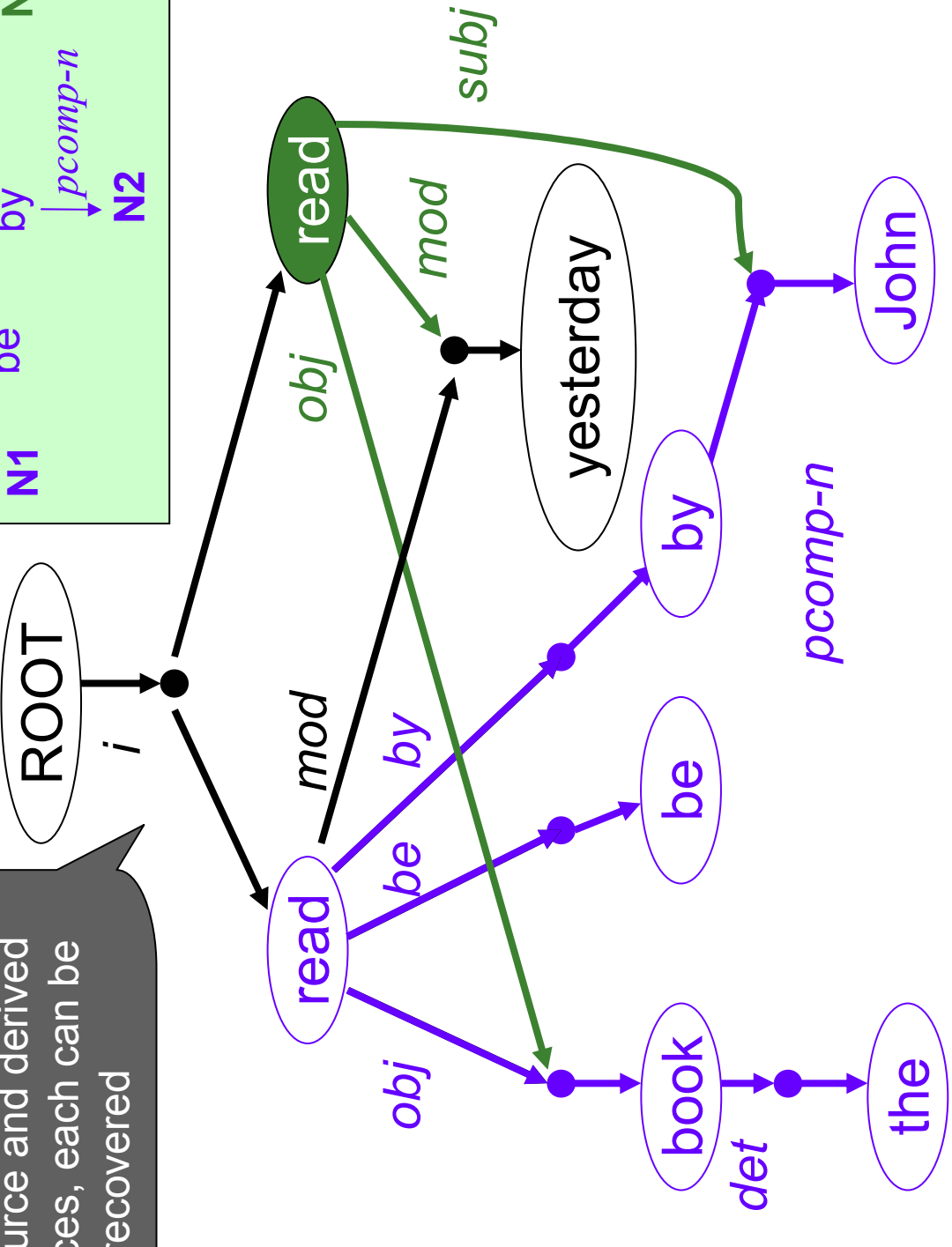
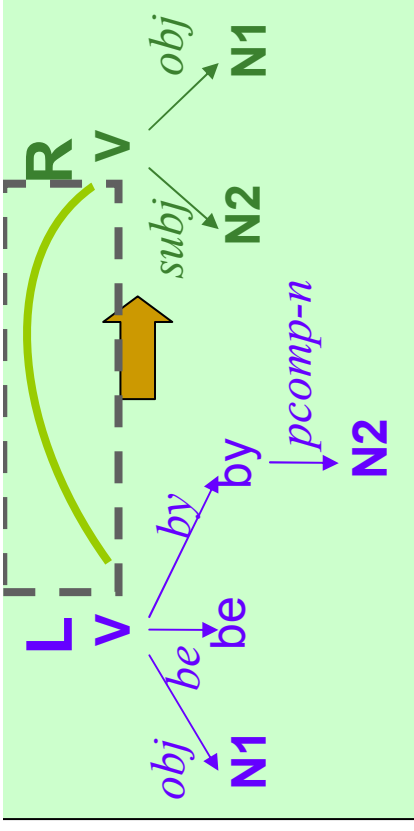
Step 5

Sharing modifiers through alignment



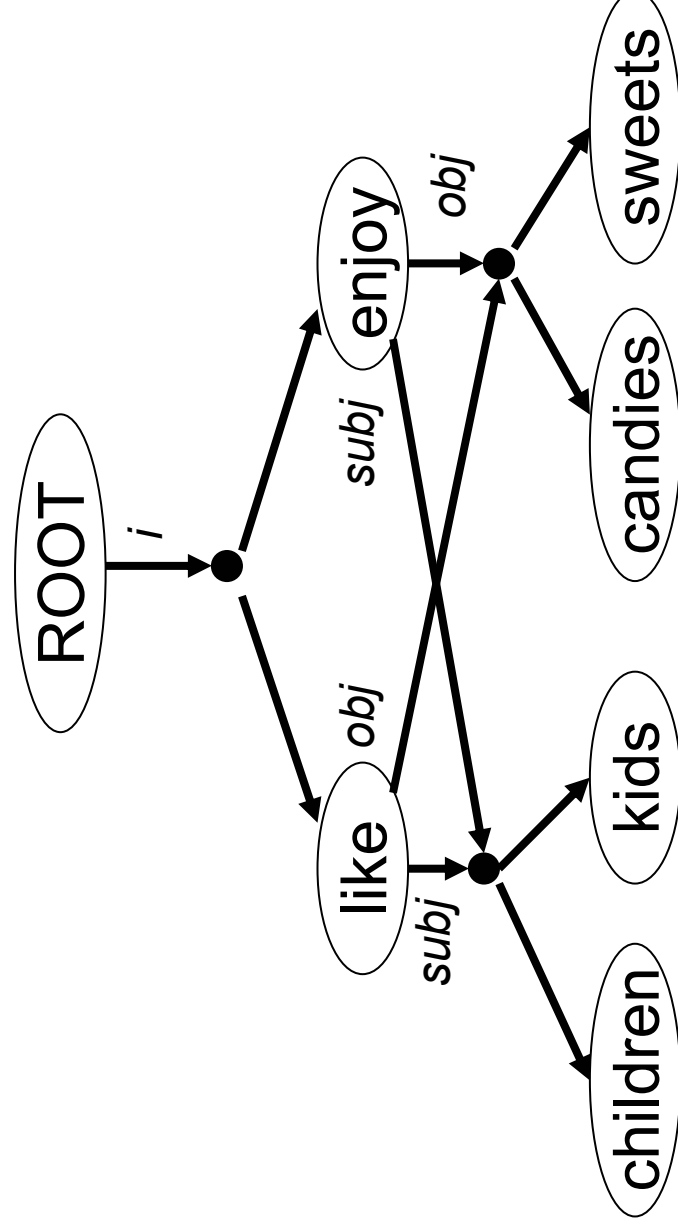
The book was read by John yesterday ⇒ John read the book yesterday

Resulting forest contains both source and derived sentences, each can be recovered



⇒ An efficient data structure, preserving inference semantics

# Children and Sweets – the Compact Version...



Complexity reduction from exponential to linear!

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# New Knowledge Sources

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# Extracting Lexical Rules from Wikipedia

## E.T. the Extra-Terrestrial

From Wikipedia, the free encyclopedia

(Redirected from E.T. (film))



***E.T. the Extra-Terrestrial*** is a 1982 science fiction film co-produced and directed by Steven Spielberg, written by Melissa Mathison and starring Henry Thomas, Robert MacNaughton, Drew Barrymore, Dee Wallace and Peter Coyote. It tells the story of Elliott (played by Thomas), a lonely boy who befriends a friendly alien dubbed "E.T." who is stranded on Earth. Elliott and his "Extraterrestrial life

- ***Be-complement***

Nominal complements of 'be'

- ***Redirect***

various terms to canonical title

- ***Parenthesis***

used for disambiguation

- ***Link***

Maps to a title of another article

# Lexical-Syntactic Rules from Lexical Resources

- Entailment rules between predicates + argument mapping
- Combining information from various lexical resources:
  - **WordNet:** semantic relations (synonyms, hyponyms)
  - **VerbNet:** subcategorization frames for verbs
  - **Nomlex-Plus:**
    - Mapping between verbs and nominalizations (acquire  $\Leftrightarrow$  acquisition)
    - Subcategorization frames for nominalizations
  - Example:  
*homicide of X by Y  $\Leftrightarrow$  killing of X by Y  $\Leftrightarrow$  Y kill X*

# Polarity Rules

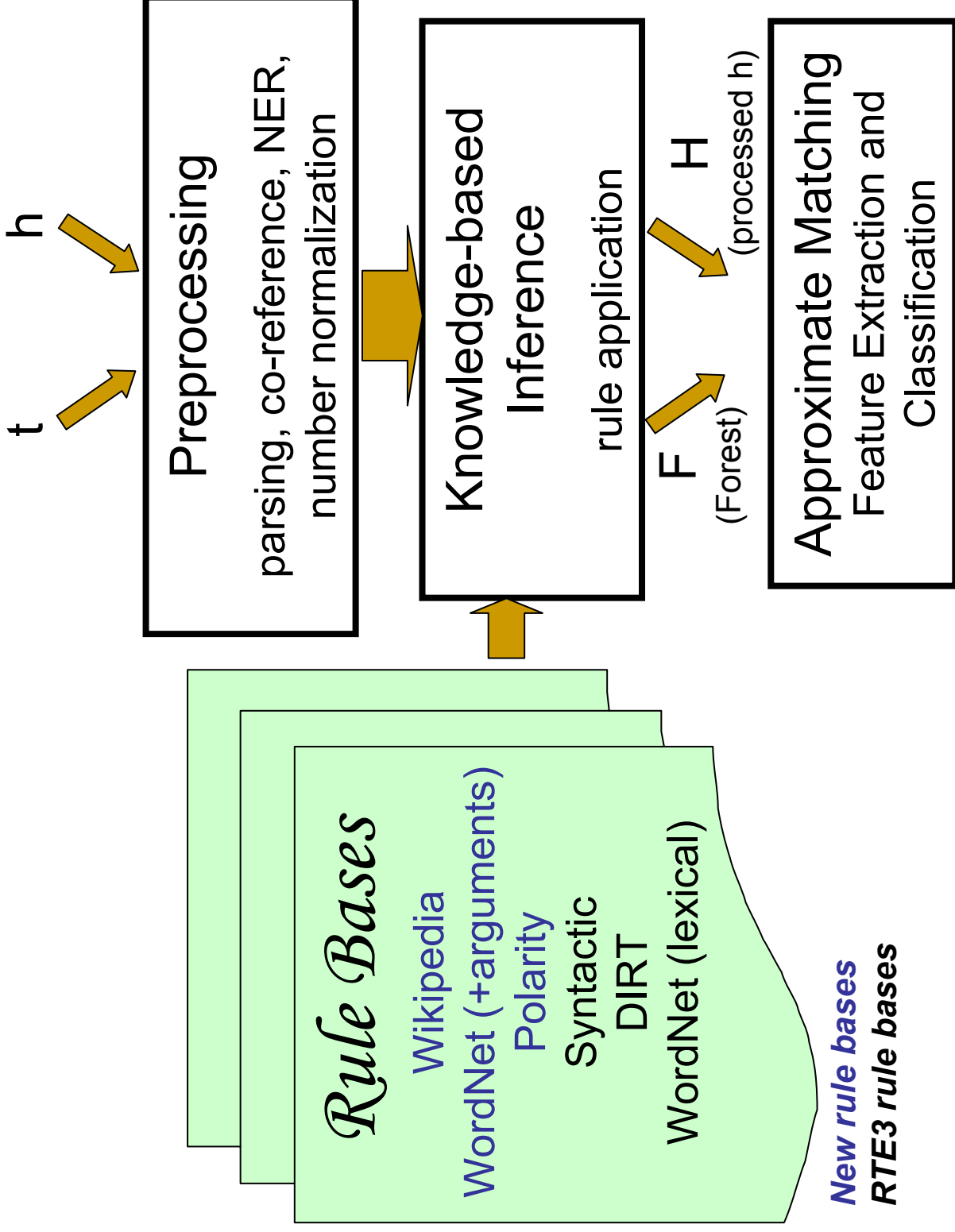
- Annotate **polarity** for verbs and Nouns
  - **Positive:** *John called<sup>(+)</sup> Mary.*
  - **Negative:** *John forgot to call<sup>(-)</sup> Mary.*
  - **Unknown:** *John wanted to call<sup>(?)</sup> Mary.*
- Expressed by
  - Verbal negation
  - modal verbs and adverbials
  - conditional sentences
  - Verbs inducing **negative** polarity - *forget, failed*
  - Verbs inducing **unknown** polarity - *want, attempt*
- Polarity mismatch is indicative for no-entailment
  - Used as feature

# Adding Approximate Matching

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# RTE4 System Architecture



# Features for Approximate Matching

- Coverage of H by F
  - Lexical coverage (words, verbs, numbers, named entities)
  - Local syntactic coverage (edges)
  - Global structural matching
    - Aim to match maximal subtrees of H in F
    - Efficient computation using dynamic programming
- Polarity mismatch (*forgot to buy vs. bought*)
- Argument matching for corresponding predicates

# Results

- Using SVM classifier (outperforms decision tree)

Train	Test	Knowledge-Based Inference	Accuracy
RTE3 Dev+Test	RTE4	✓	58.4
RTE3 Dev	RTE4	✓	<b>60.3</b>
RTE3 Dev	RTE3 Test	✓	66.9
RTE3 Dev	RTE3 Test		64.6
RTE3 Dev	1/2RTE4	✓	58.8
RTE3 Dev	1/2RTE4		55.8

- Competitive accuracy on RTE-3 (~4-6 out of 26)
- Knowledge-based inference improves accuracy (+3%)
- New efficient architecture reduced running time from hours to minutes, allowing application of many more rules

# Conclusion

- ❑ **Takeouts**
  - A formalized proof system over parse trees can be implemented **efficiently**
    - ❑ While preserving semantics – equivalent to explicit generation of consequents
    - ❑ Substantial run time reduction
    - ❑ Substantial increase in number of rules applied
  - Knowledge helps!
    - ❑ But not much for now...
- ❑ **Future research**
  - Analysis (errors, missing knowledge, impact of resources, search strategies)
  - Additional knowledge sources
  - Improve approximate matching

**Thank you!**